TRANSONIC FLOW CALCULATIONS

FOR AIRFOILS

AND BODIES OF REVOLUTION

by

Antony Jameson

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Grumman Aerospace Corporation

### 1. Introduction

This report presents results of transonic flow calculations by the relaxation method for a selection of airfoils and bodies of revolution. The flow is assumed to be determined by the potential flow equation

$$(a^2-u^2) \varphi_{xx} - 2uv \varphi_{xy} + (a^2-v^2) \varphi_{yy} = 0$$
 (1.1)

where  $\phi$  is the potential, u and v are the velocity components

$$u = \varphi_{x}, \quad v = \varphi_{y} \tag{1.2}$$

and a is the local speed of sound. This may be determined from the stagnation speed of sound a by the energy equation

$$a^2 = a_0^2 - .2 (u^2 + v^2)$$
 (1.3)

in which the ratio of the specific heats has been taken as 1.4. If the velocities are normalized with unit free stream velocity, then

$$a_0^2 = \frac{1}{M^2} + .2$$
 (1.4)

where M is the free stream Mach number.

There is no assumption of small disturbances and the solution would be exact for subsonic flow in the absence of viscosity. In transonic flow the principal approximation is the neglect of rotation introduced by shock waves. In the absence of rotation Crocco's theorem [1] indicates that the flow is homentropic. The solution must allow discontinuities to approximate to approximate shock waves, and it has been shown by Morawetz [2] that in general a continuous solution does not exist in transonic flow. Since in isentropic flow there is a unique relation between velocity and area along a stream tube, the interpretation of a solution with a jump in velocity is that it is a solution in the presence of a fictitious screen just the correct throat area to permit an isentropic compression. Since there is a pressure differential on either side of the throat a discontinuity in the solution

represents a line carrying a force. The total drag is zero in potential flow, so this force is just balanced by a drag on the airfoil, and it turns out that the solution can be used to obtain an estimate of the pressure drag on the airfoil in the presence of a shock wave (see the results).

It should also be noted that in the absence of a directional condition corresponding to the condition that entropy can only increase, the solution of the potential equation is not unique. Given a solution, the equation continues to be satisfied when the velocity is reversed. Thus, for example, a body with for and aft symmetry always admits a solution with a reverse shock as well as one with a forward shock. In order to obtain a unique solution, it is necessary to introduce directionality into the difference scheme used to approximate the equation. Following Murman [3], this is accomplished by using a central difference scheme in the subsonic region together with a backward difference scheme in the supersonic region.

### 2. Formulation of the equations in the circle domain.

In order to obtain a finite domain of calculation the flow field is first mapped to the interior of a unit circle by a conformal transformation, following Sells [4]. Using polar coordinates r and  $\theta$ , the potential for a uniform at angle  $\alpha$  would then be  $\frac{\cos(\theta+\alpha)}{r}$ . Also, in the presence of circulation the potential would be multiple valued. It is convenient therefore to set

$$\phi = X + \frac{\cos(\theta + \alpha)}{r} - E\theta$$
 (2.1)

where  $2\pi E$  is the circulation, and solve for the reduced potential functions X which is finite and everywhere continuous. Let the modulus of the transformation to the interior of the circle be  $\frac{H}{r}2$ . H is the modulus of the transformation to the exterior of the circle, and is a smooth function suitable for differencing. The equation for X in polar coordinates then becomes

$$(a^{2} - u^{2}) X_{\theta\theta} - 2uv (rX_{\theta r} + X_{\theta} - E) + (a^{2} - v^{2})(r^{2}X_{rr} + rX_{r})$$

$$+ (u^{2} - v^{2})rX_{r} + (u^{2} + v^{2})(\frac{u}{r}H_{\theta} + vH_{r}) = 0$$
(2.2)

where

$$u = r(X_{\theta} - E) - \sin(\theta + \alpha), \quad v = \frac{r^2 X_r - \cos(\theta + \alpha)}{H}$$
 (2.3)

and

$$a^2 = a_0^2 - .2(u^2 + v^2)$$
 (2.4)

The boundary condition at the surface r = 1 is

$$\mathbf{v} = 0, \ \mathbf{X}_{\mathbf{r}} = \cos \left( \theta + \alpha \right) \tag{2.5}$$

If the airfoil has a sharp trailing edge, it is convenient to orient the circle so that the corresponding point is at  $\theta=0$ . At this point H=0, and the Kutta condition that the velocity is finite at the trailing edge then requires that

$$X_{A} = E + \sin \alpha \tag{2.6}$$

Also the equation for X can be written as

$$a^{2}(r^{2}X_{rr} + rX_{r} + X_{\theta\theta}) = Hu \frac{1}{r} \frac{\partial}{\partial \theta} (\frac{u^{2} + v^{2}}{2}) + Hv \frac{\partial}{\partial r} (\frac{u^{2} + v^{2}}{2})$$

At the trailing edge, the right side vanishes and thus X locally satisfies Laplace's equation.

At the center of the circle H  $\rightarrow$  1 + 0( $r^2$ ), u  $\rightarrow \sin(\theta + \alpha)$ , v  $\rightarrow \cos(\theta + \alpha)$ ,

 $a \rightarrow \frac{1}{2}$ . It can be seen therefore that the potential equation reduces to

$$[1-M^2 \sin^2(\theta+\alpha)] X_{\theta\theta} -2M^2 \sin(\theta+\alpha) \cos(\theta+\alpha)(X_{\theta}-E) = 0$$
 (2.7)

This can be integrated to give the far field boundary condition at 
$$r = 0$$

$$X = E \left\{ \theta - \tan \left[ (1 - M^2)^{\frac{1}{2}} \tan (\theta + \alpha) \right] \right\}$$
 (2.8)

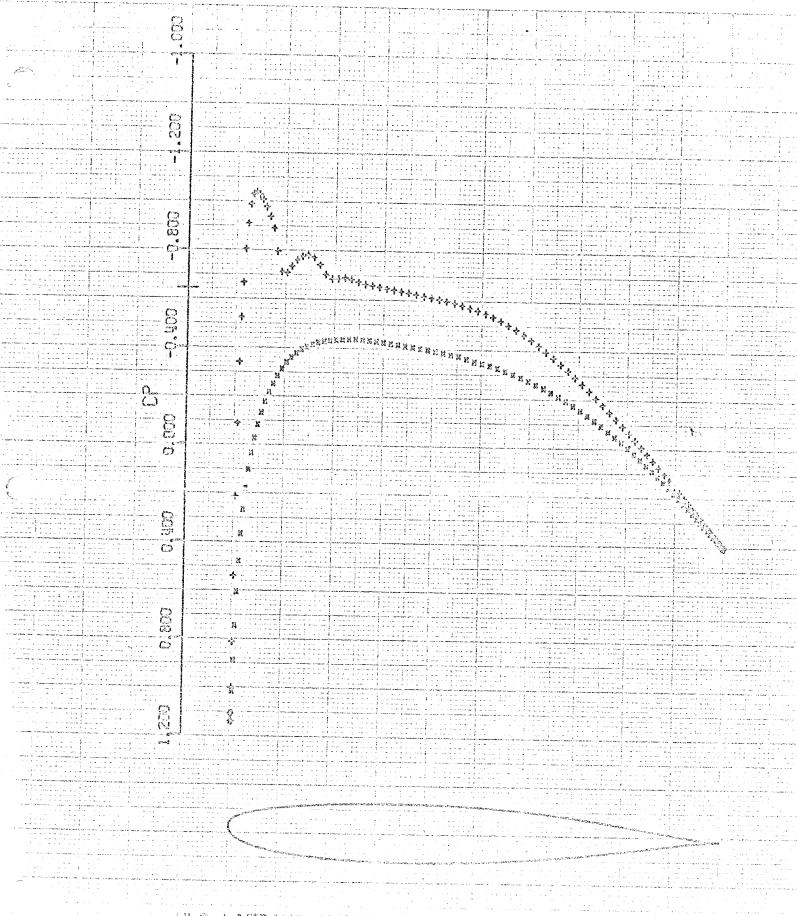
in agreement with the results of Ludford [5], and Imai [6].

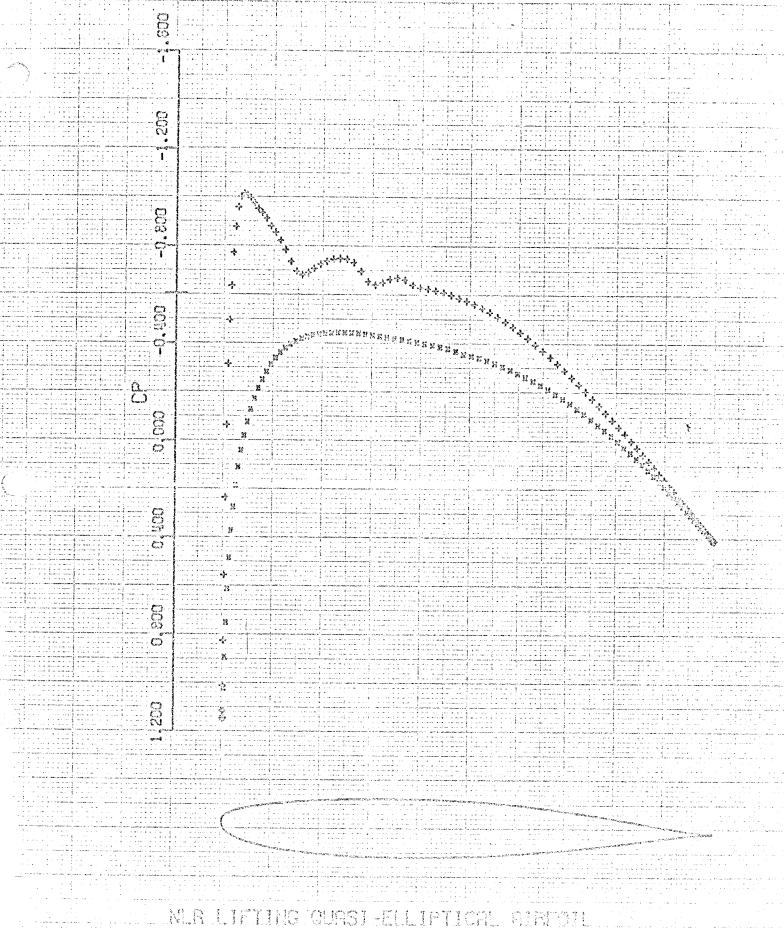
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- H. W. Liepman and A. Roshko, Elements of Gas Dynamics,
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- 2. C. S. Moraw etz, On the Non-Existence of Continuous Transcnic Flows
  Past Profiles, Comm. Pure Appl. Math, Vol. 9, 1956, pp 45 68
- 3. E. M. Murman and I. D.Cole, Calculation of Plane Steady Transonic Flows, AIAA J. Vol. 9, 1971, pp 114 121
- 4. C. C. L. Sells, Plane Subcritical Flow Past a Lifting Airfoil, Proc. Roy. Soc. Series A, Vol. 308, 1967, pp 377 401
- 5. G. S. S. Ludford, The Behaviour at Infinity of the Potential Function of a Two Dimensional Subsonic Compressible Flow J. Math Phys. 1951, Vol. 30, 1951 pp 131 139
- 6. I. Imai, Approximation Methods in Compressible Fluid Dynamics,
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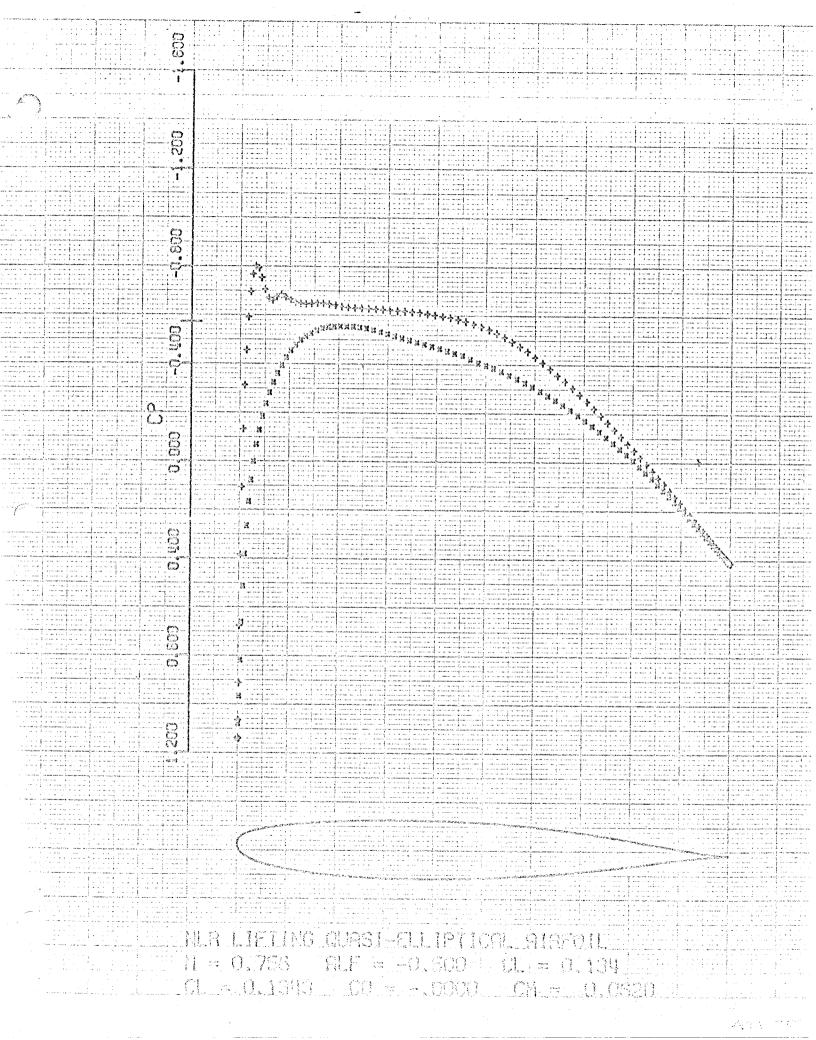
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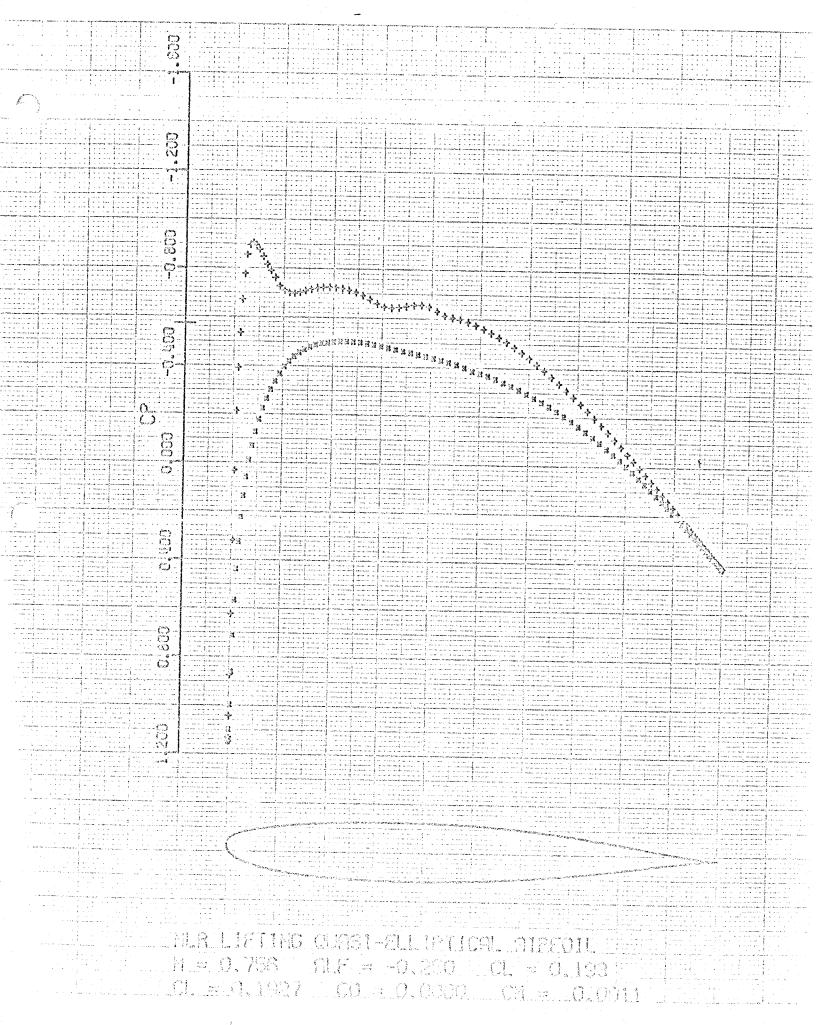
Designed to be shock free at M = .7557,  $\lambda = 0^{\circ}$  (1.32° when the coordinates are referred to the line from the maximum forward point to the trailing edge). Coordinates and slopes from AGARD Report 575, Test Cases for Numerical Methods in Two Dimensional Transonic Flow, by R. C. Lock, 1970.

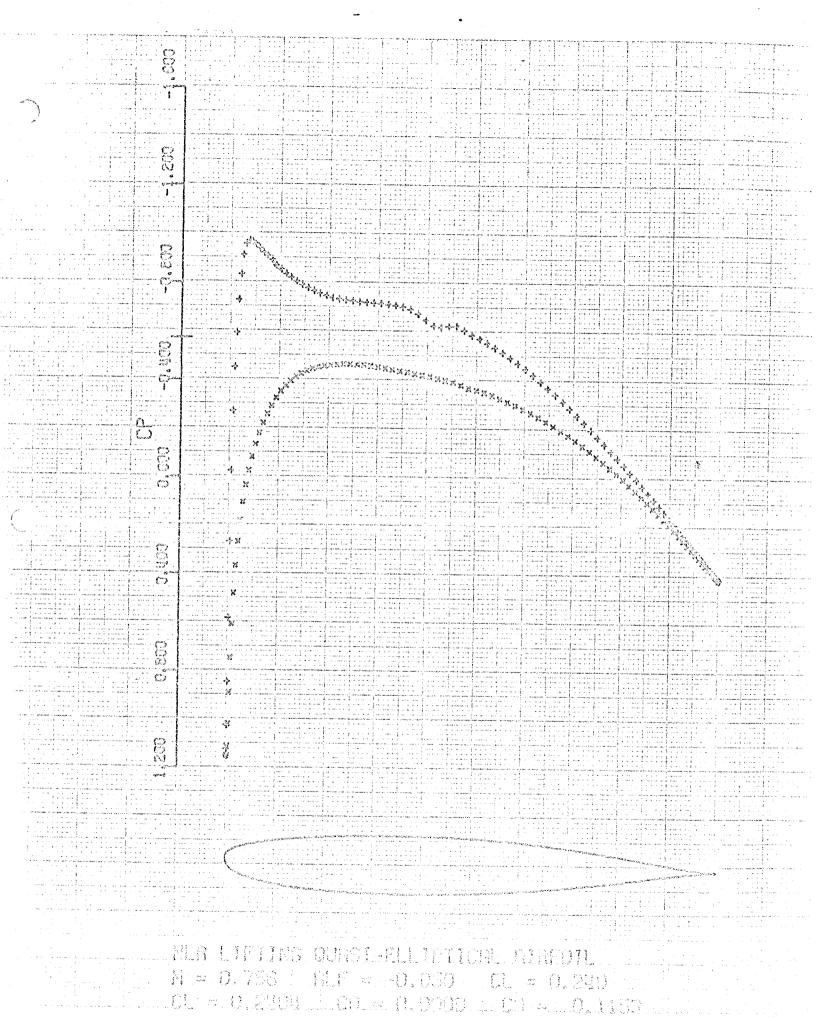


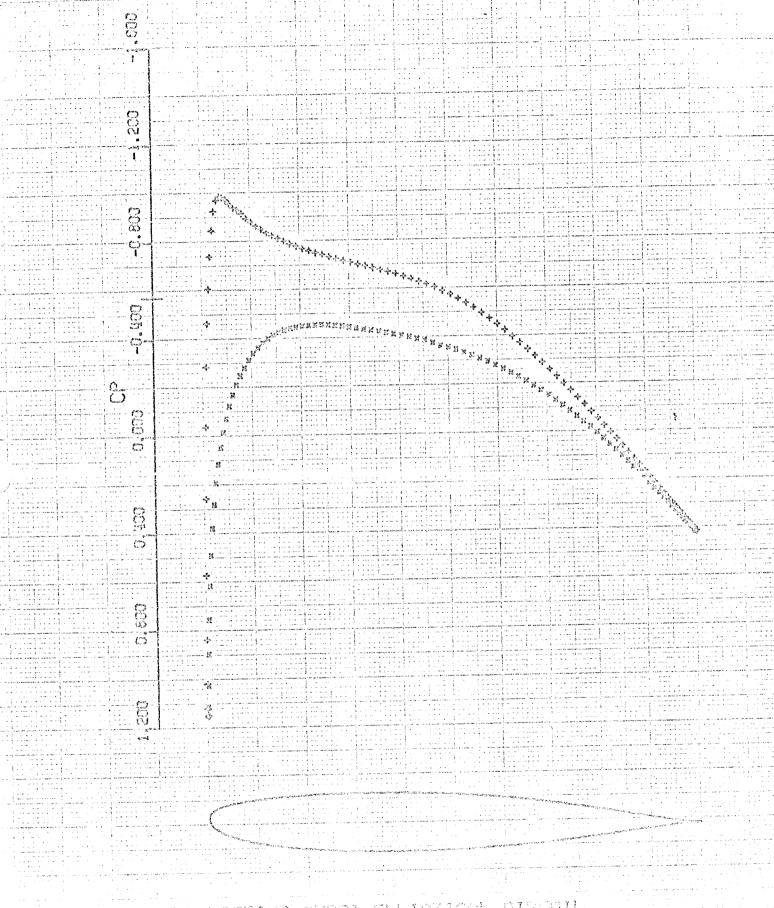


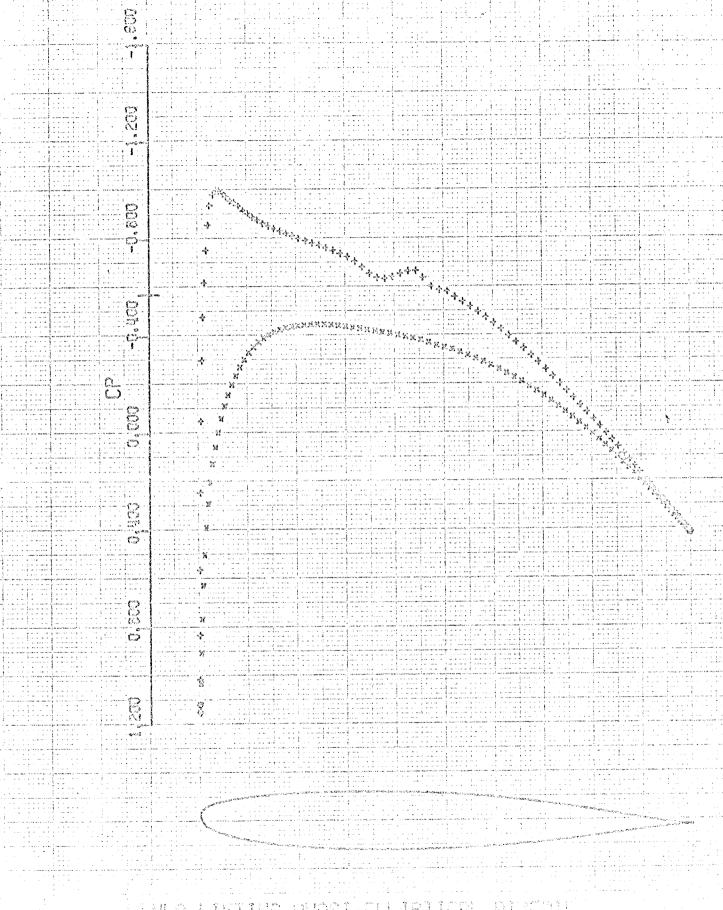
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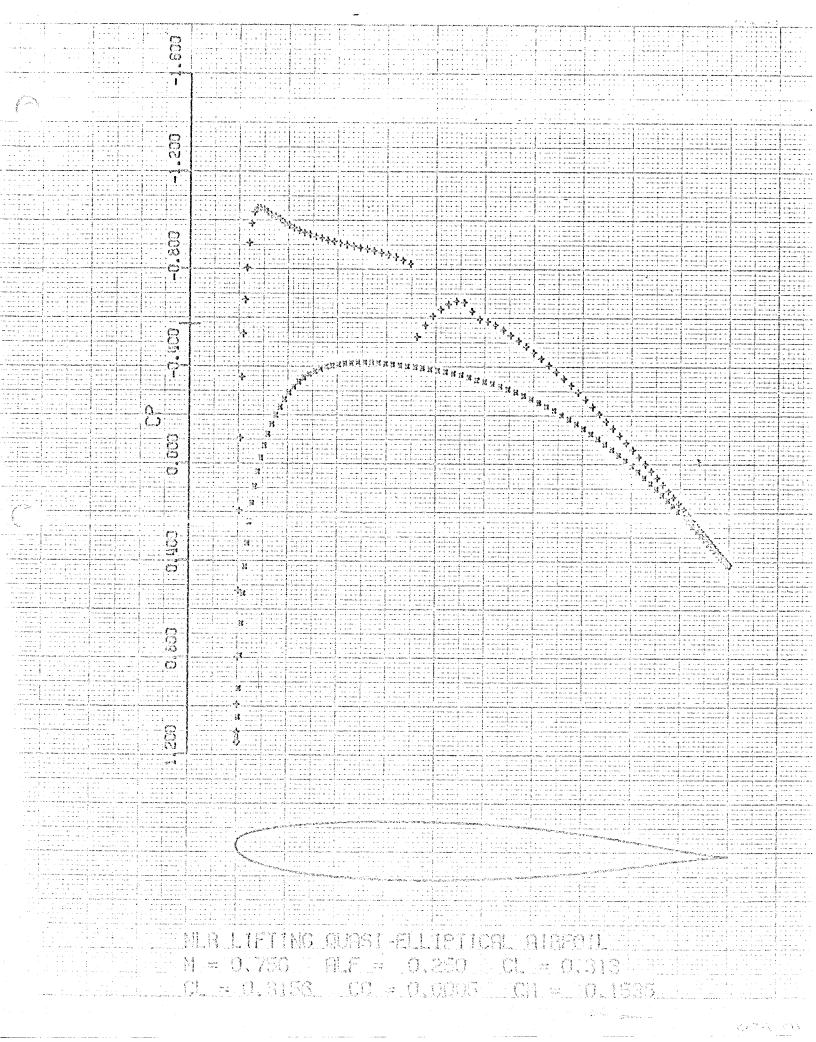


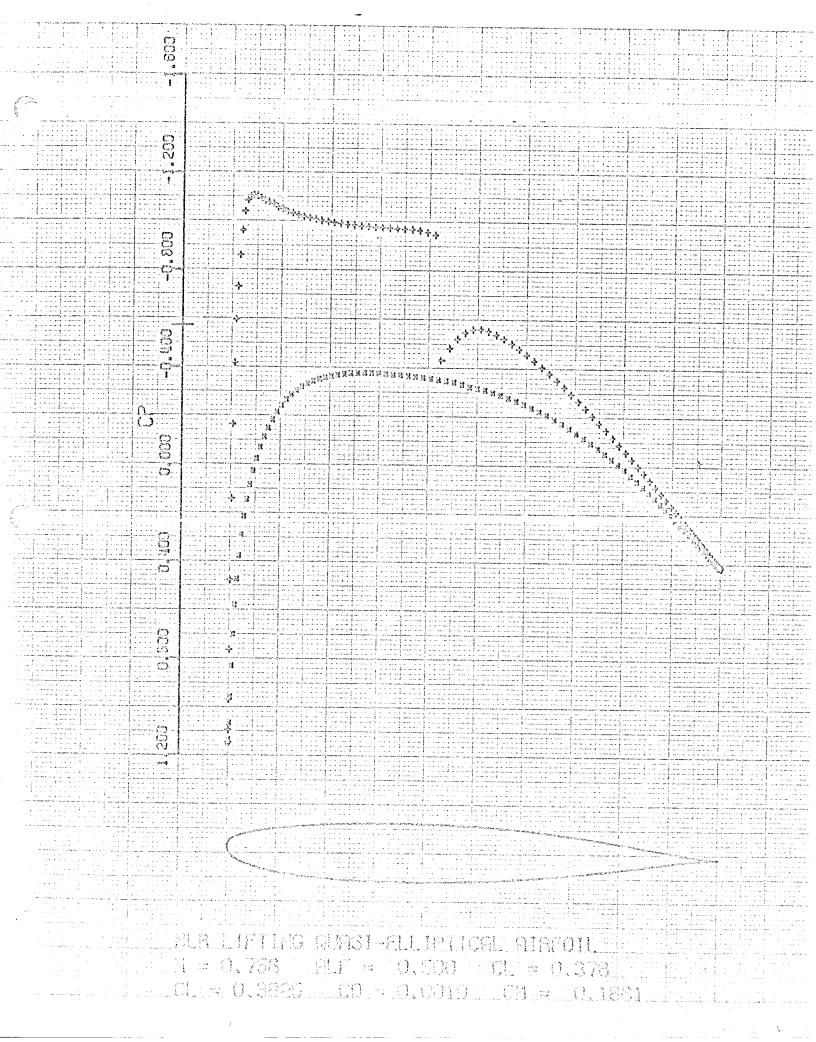


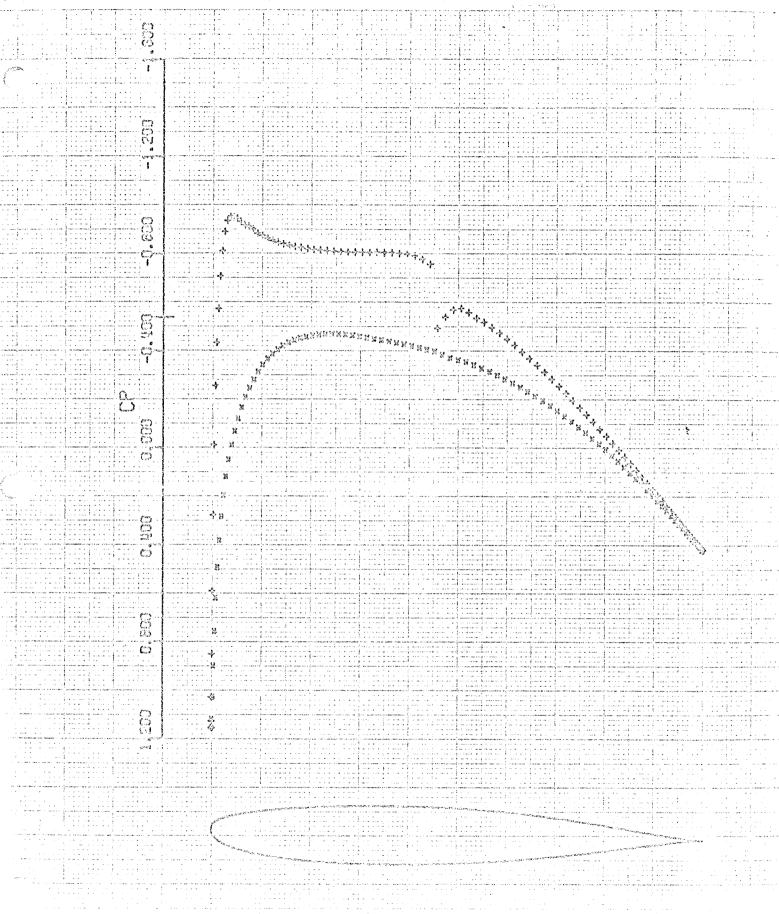




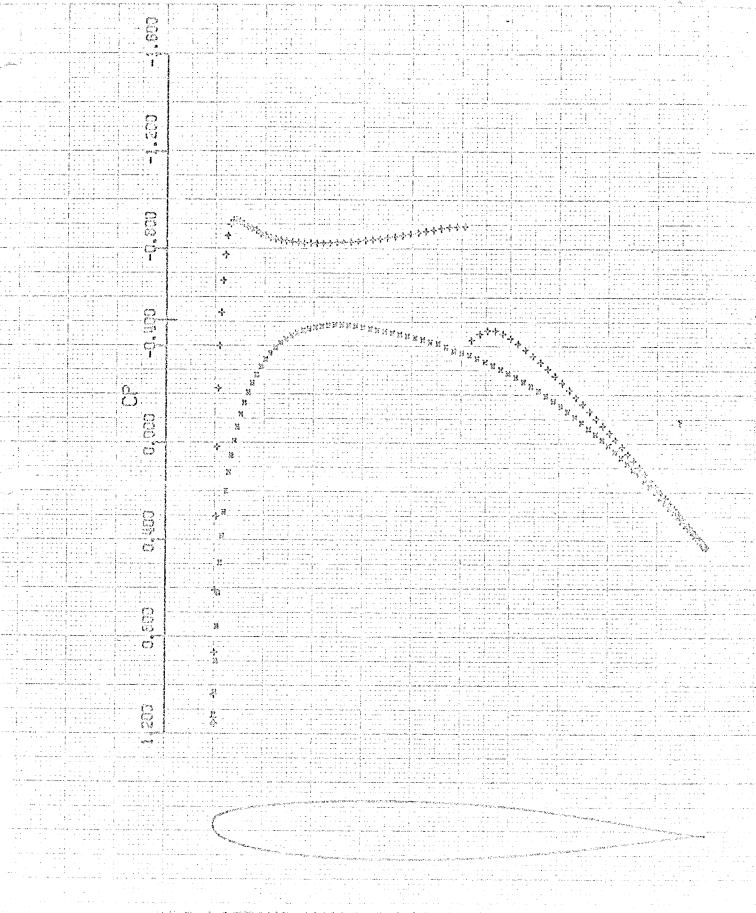








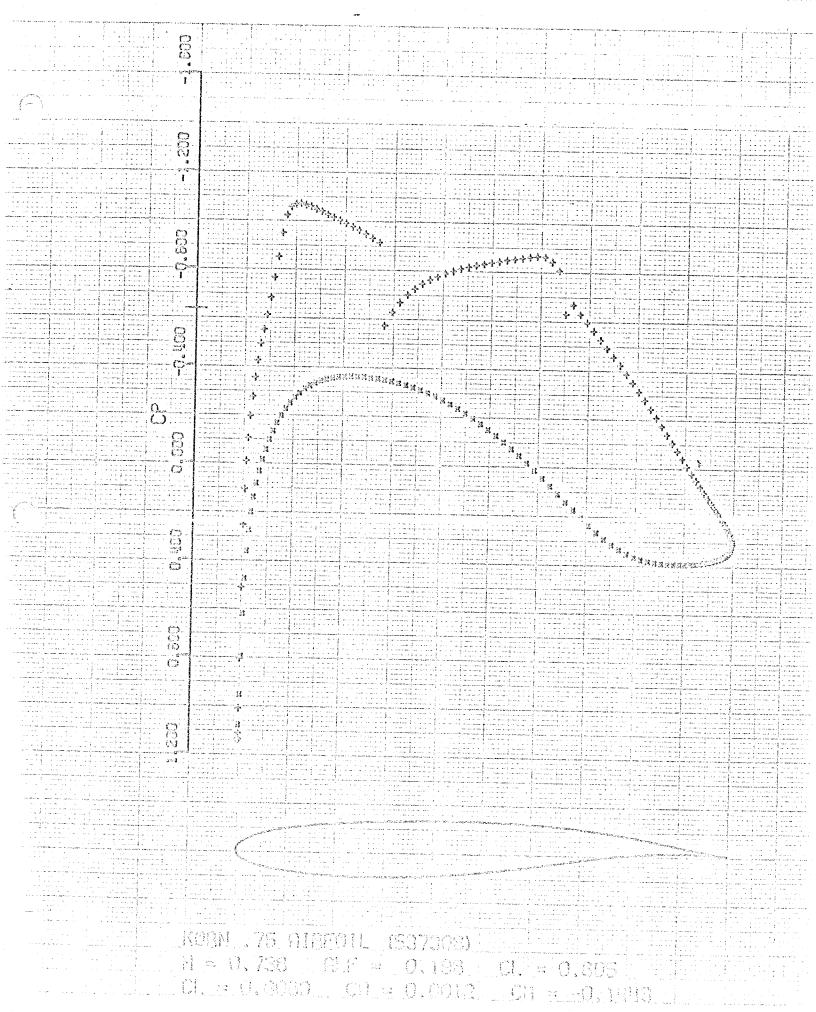
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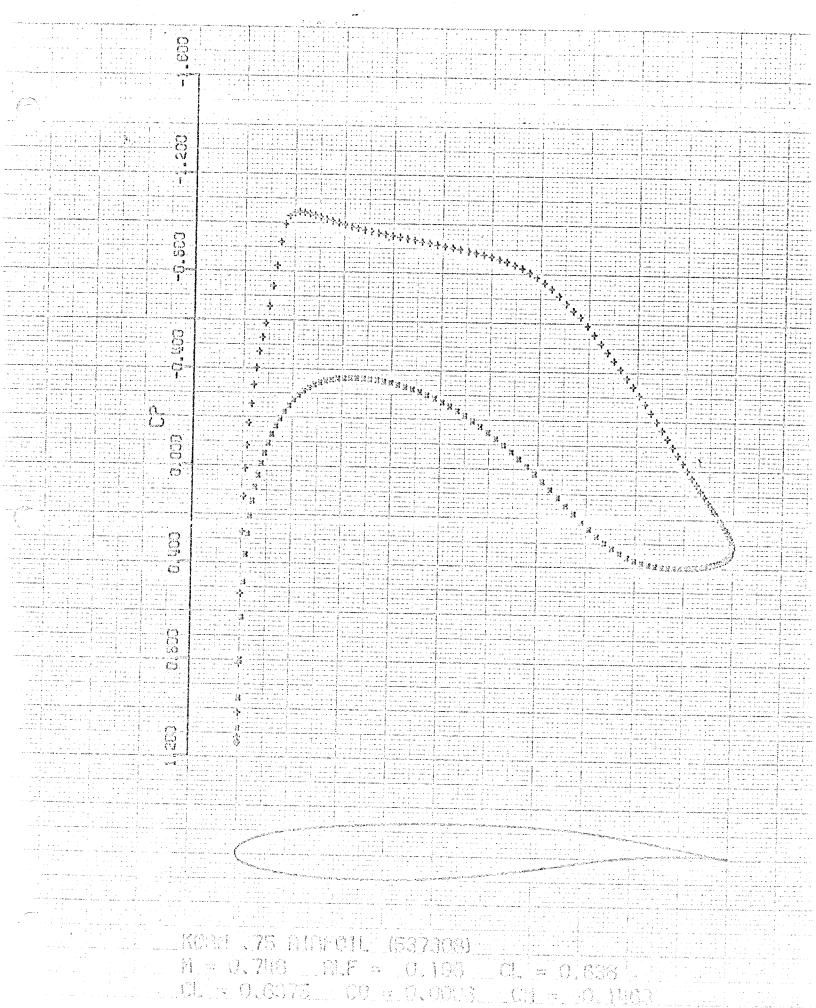


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## KORN AIRFOIL

Designed to be shock free at M = .75,  $\angle$  = .118°. Coordinates and slopes generated by Grumman's version of the Korn synthesis program.





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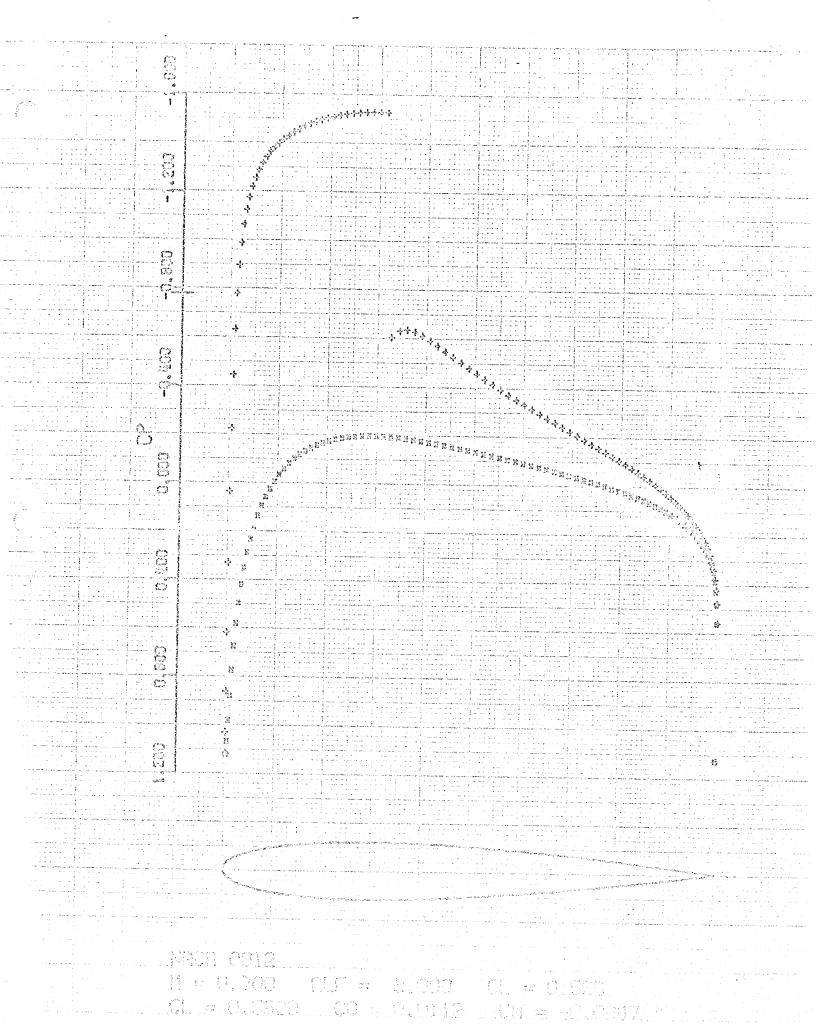
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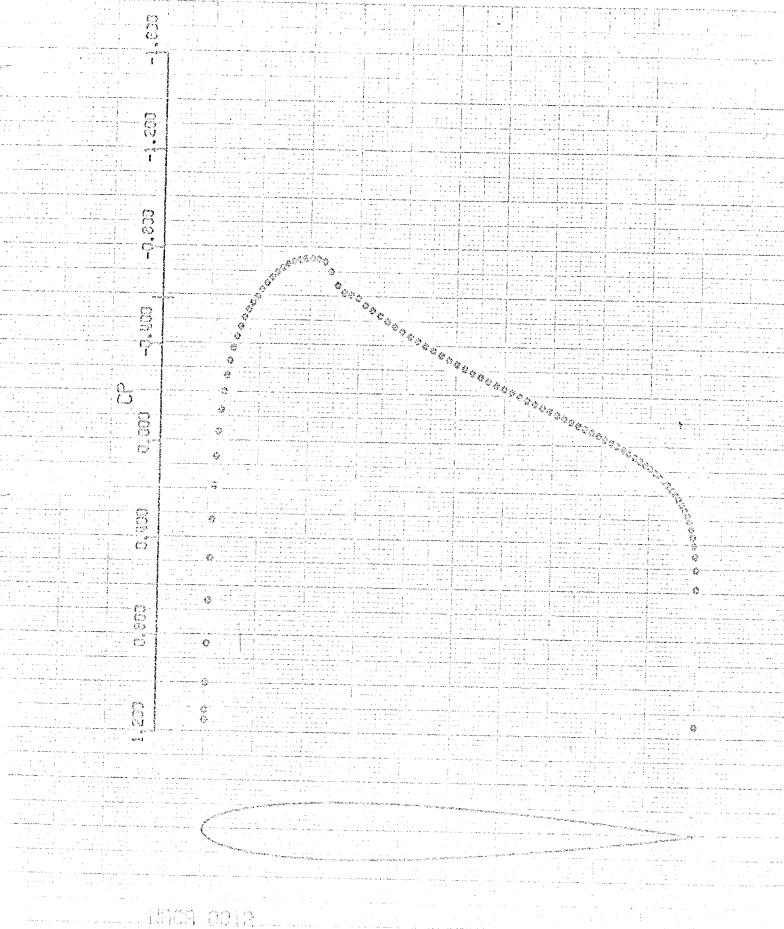
Coordinates from NAE Report LTR-HA-2, Fortran IV Program for the Catherall-Foster-Sells Method for Calculation of the Plane Inviscid Compressible Flow Past a Lifting Airfoil, by J. J. Kacprzynski, 1970.

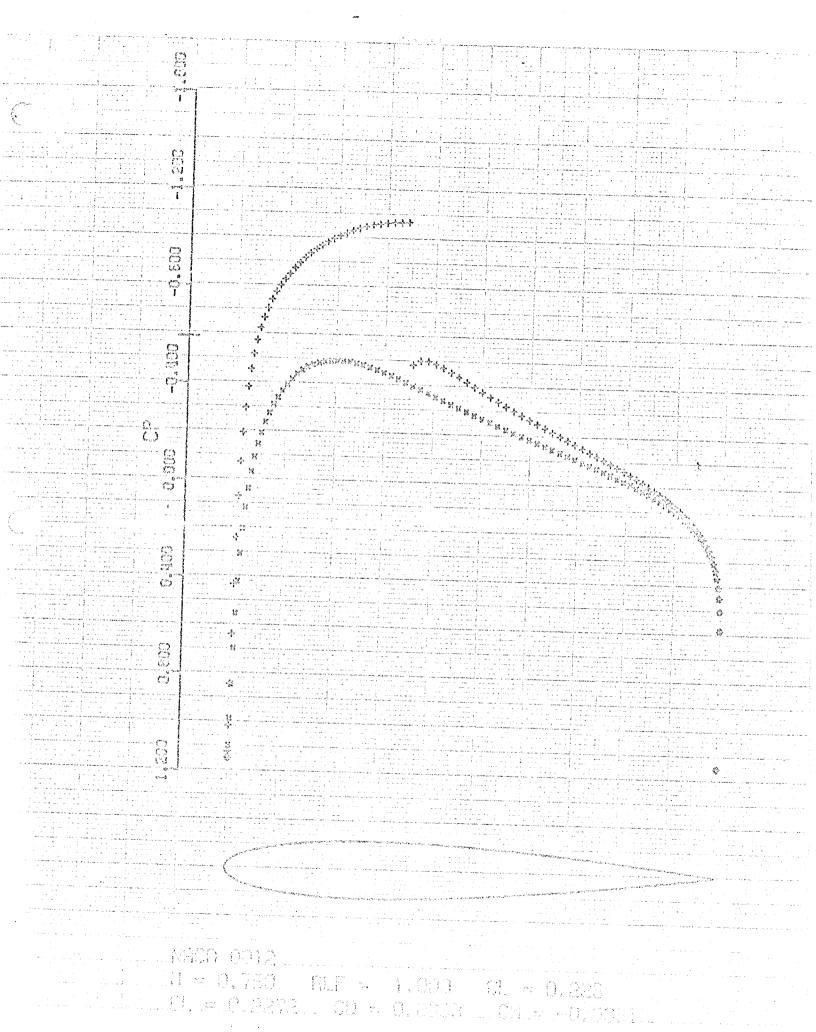




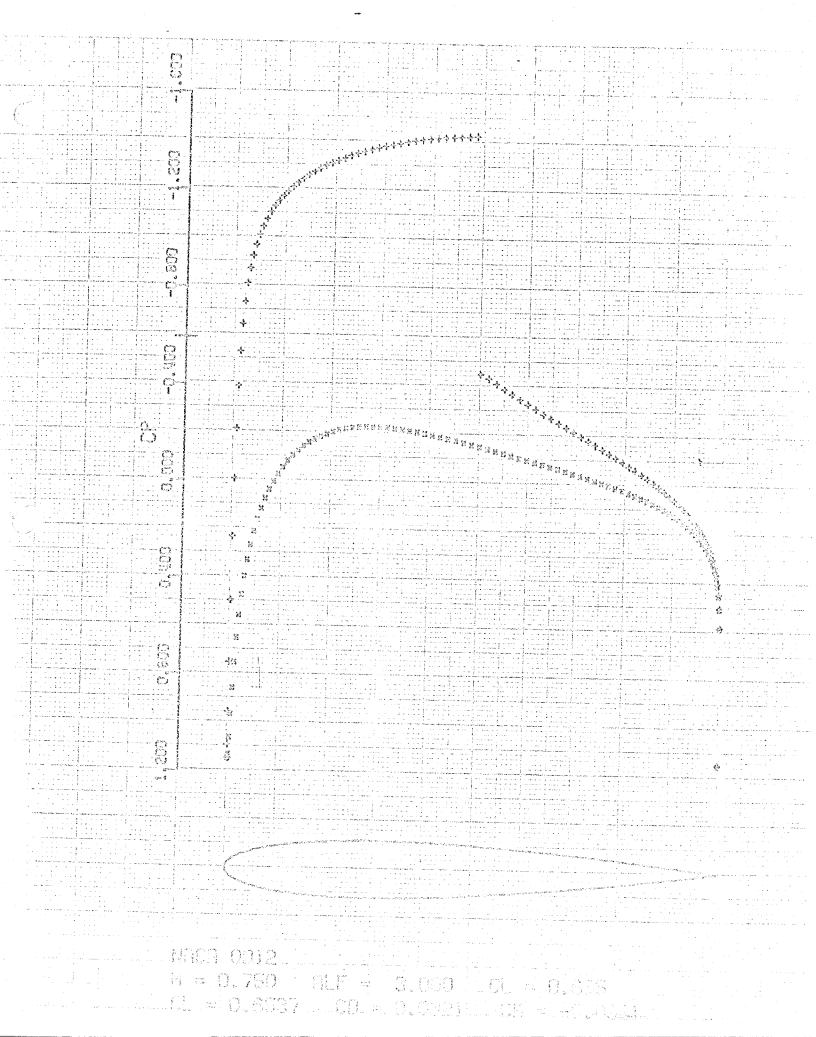


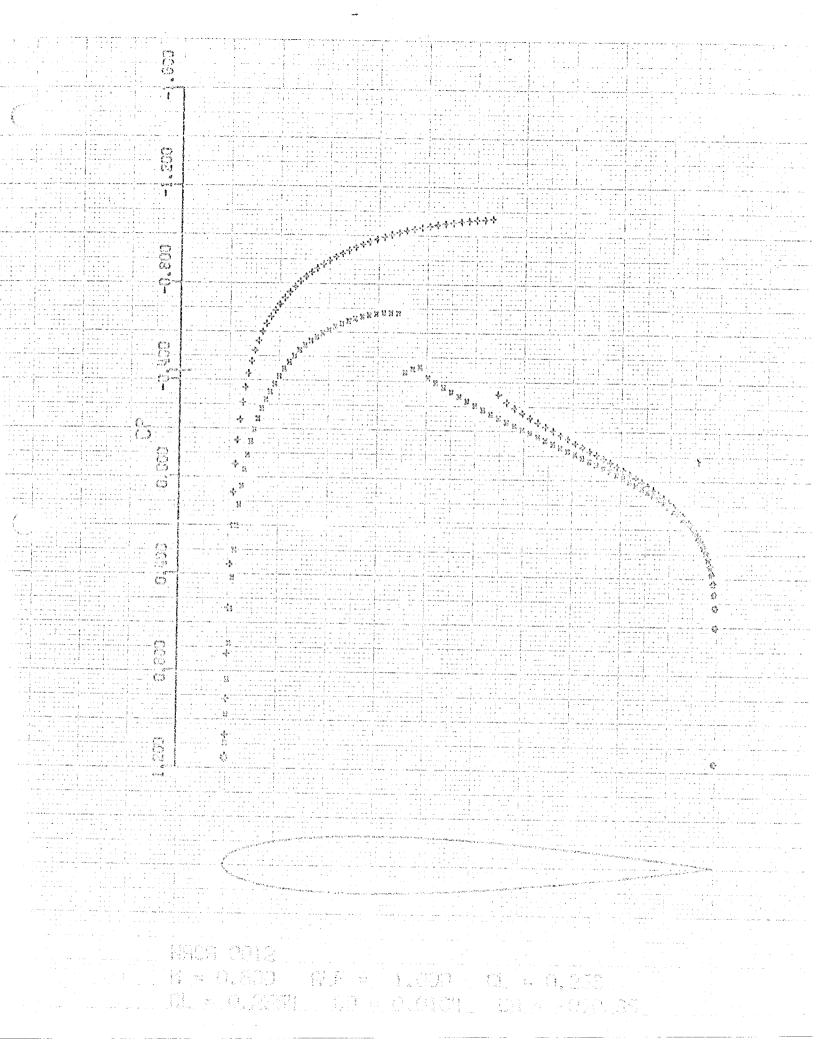


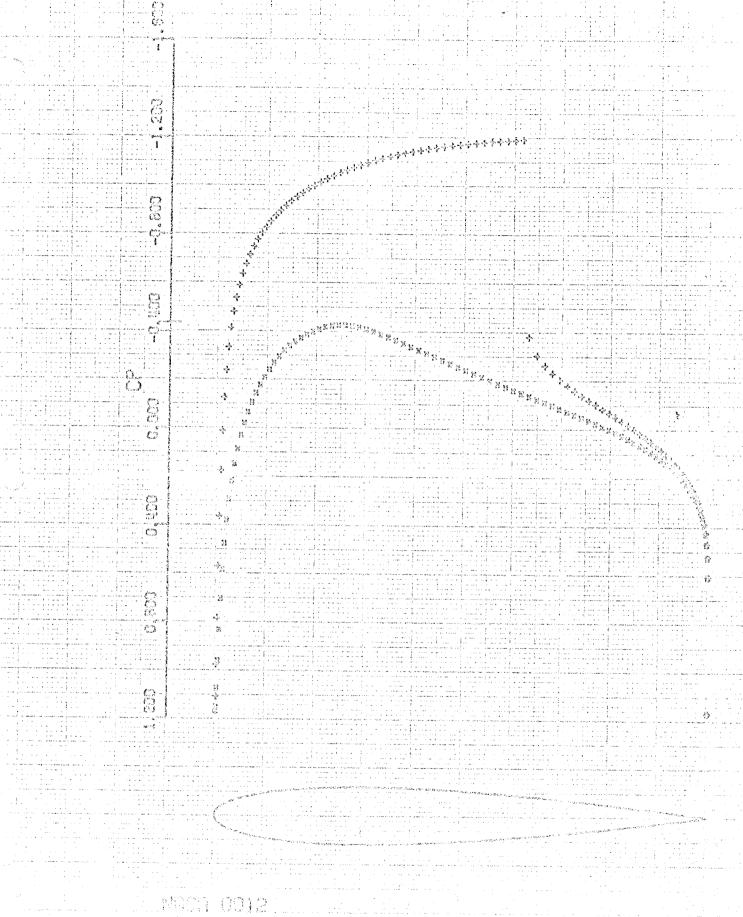


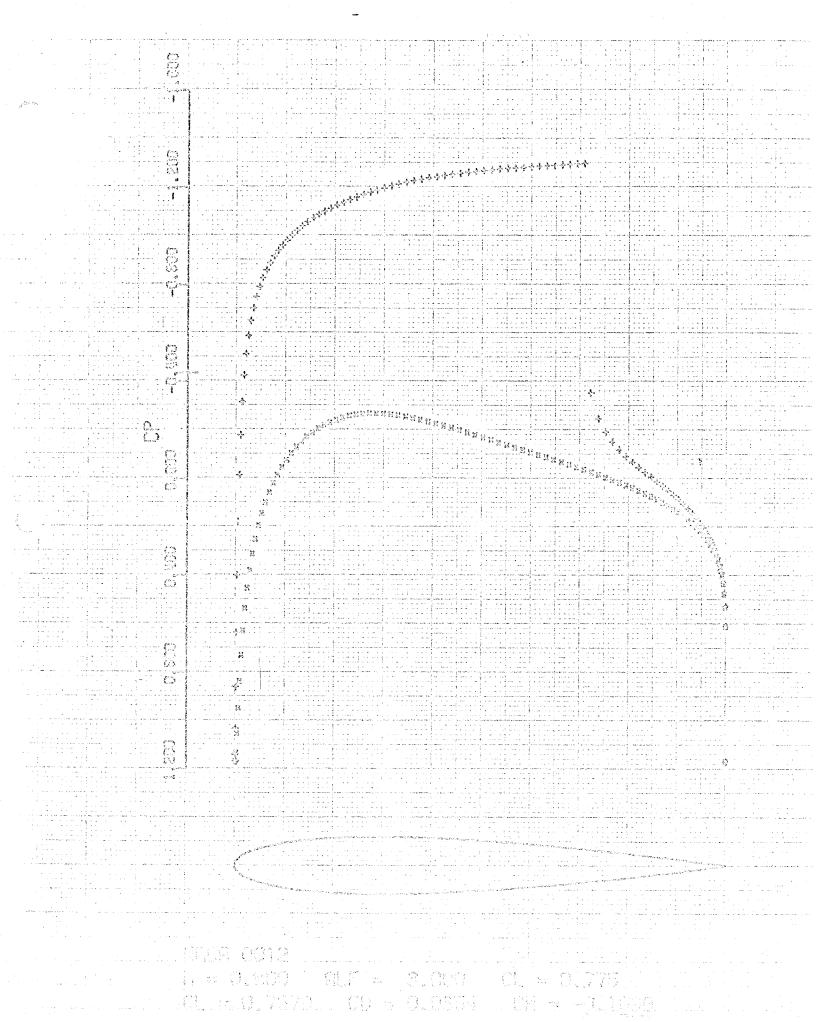






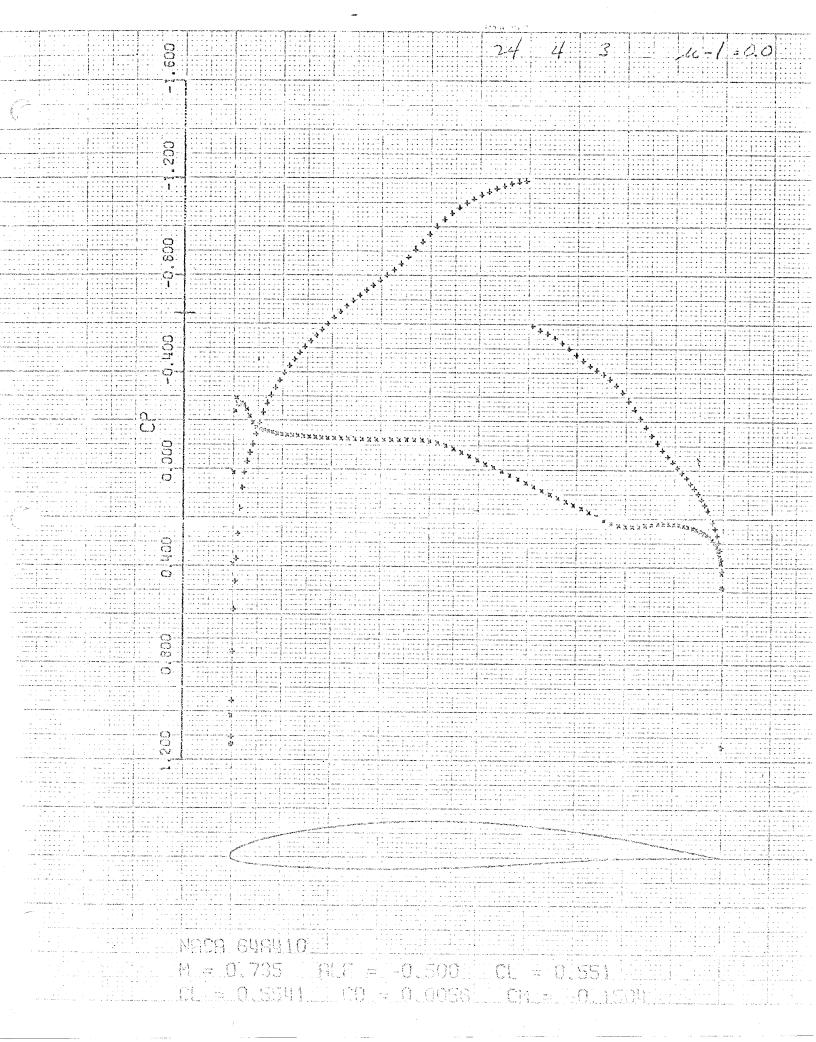


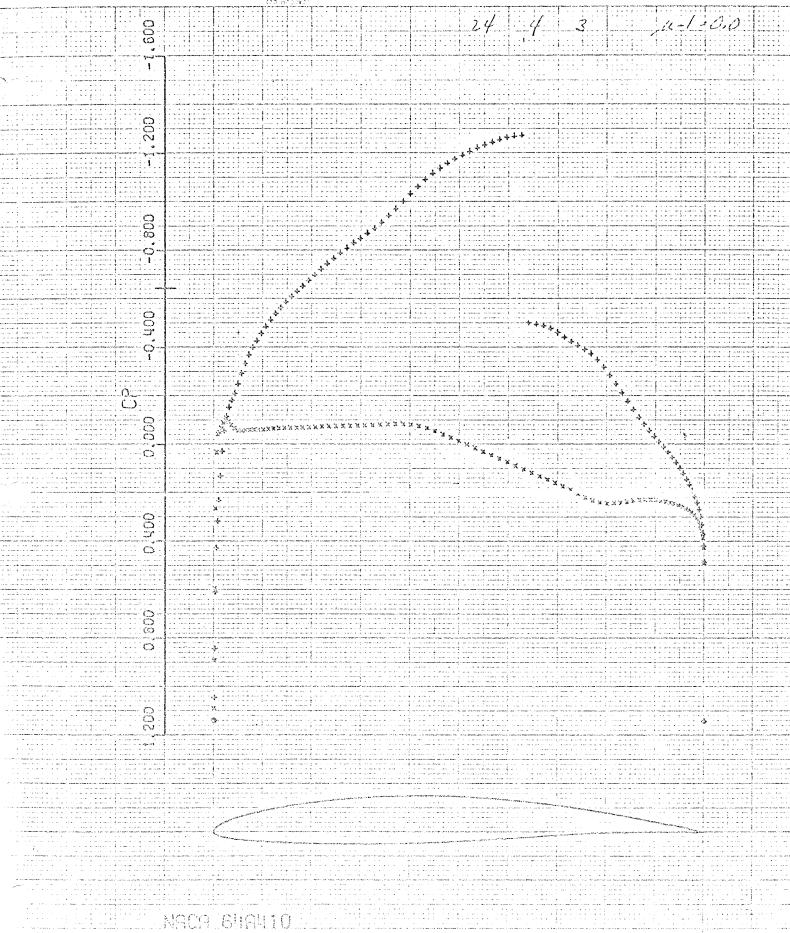


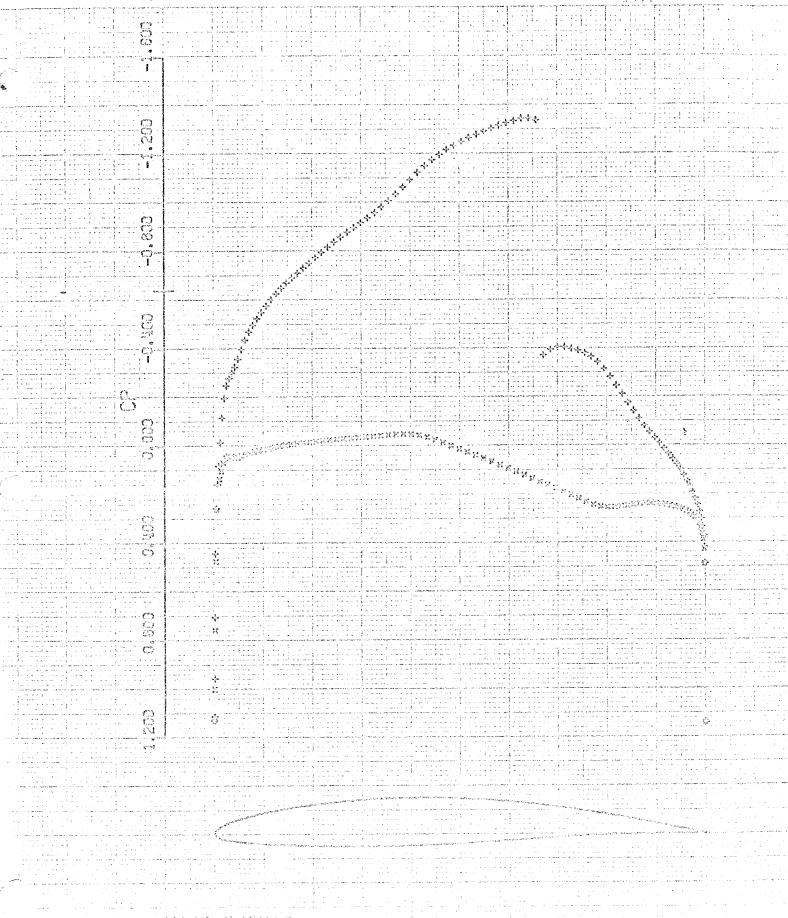


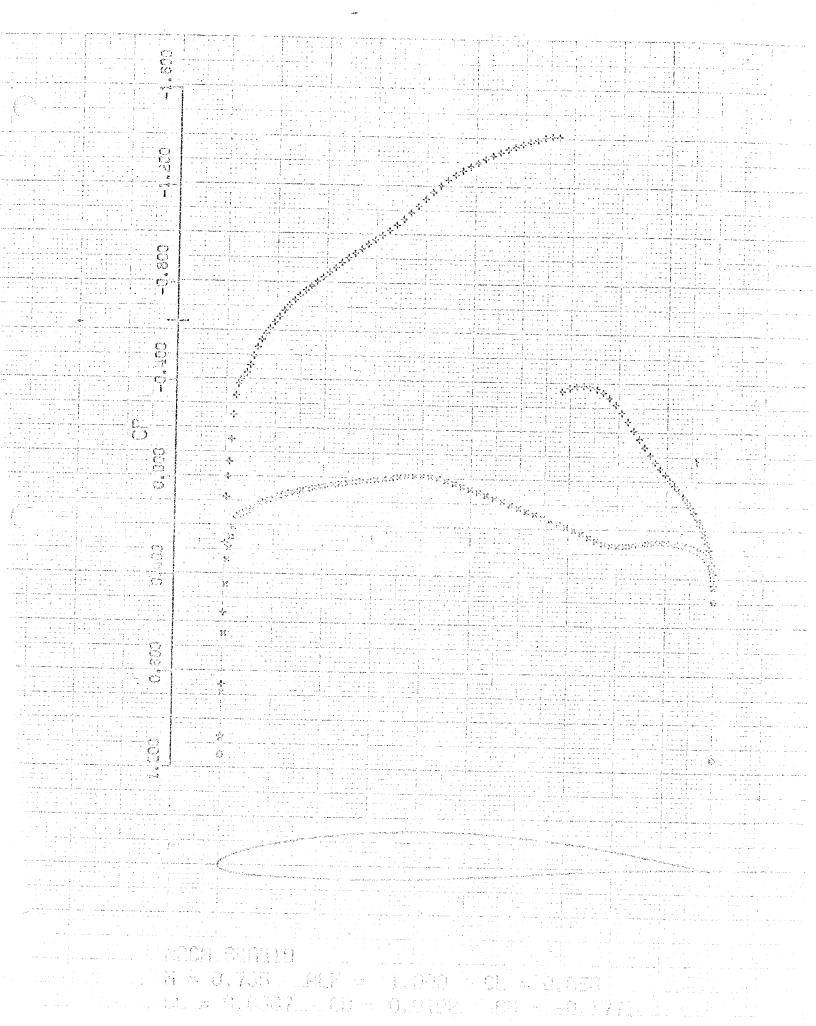
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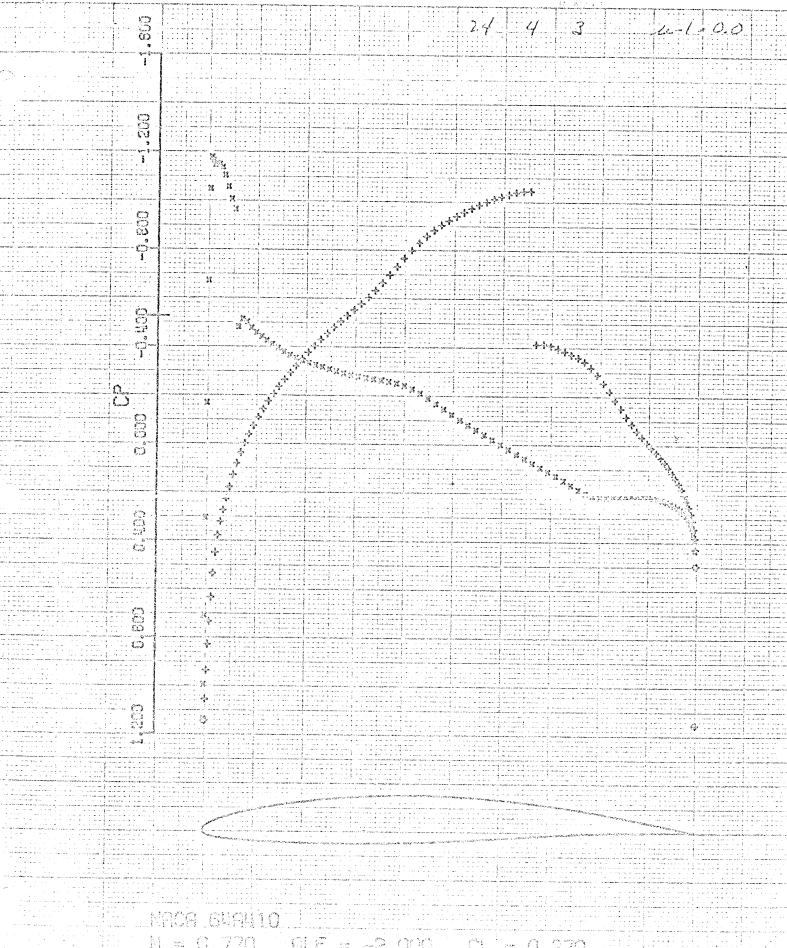
Coordinates from NACA TN 3162, Effects of Subsonic Mach Number on the Forces and Pressure Distributions on Four NACA 64A - Series Airfoil Sections at Angles of Attack as High as 28°, by Louis S. Stivers, 1954.



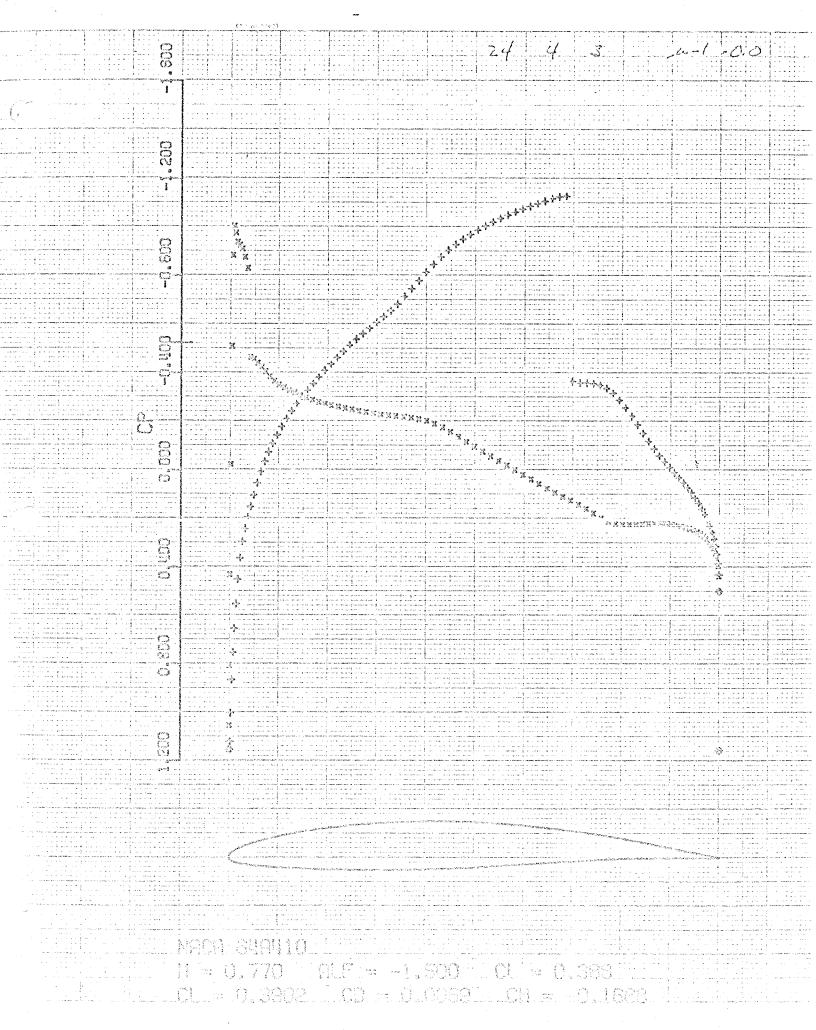


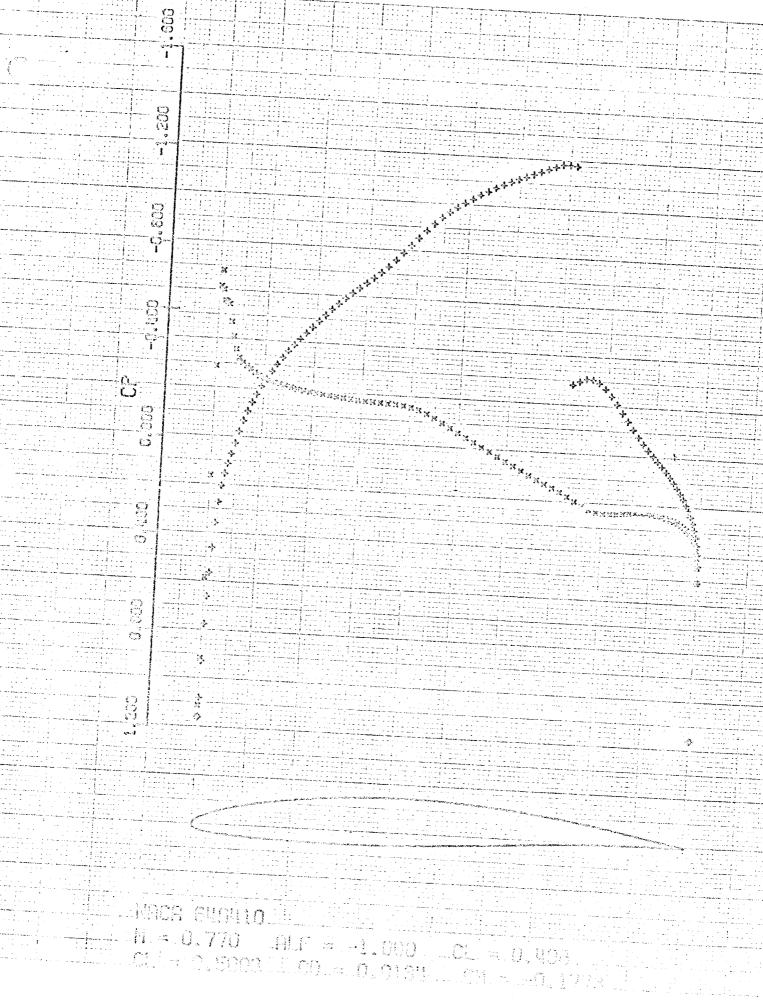


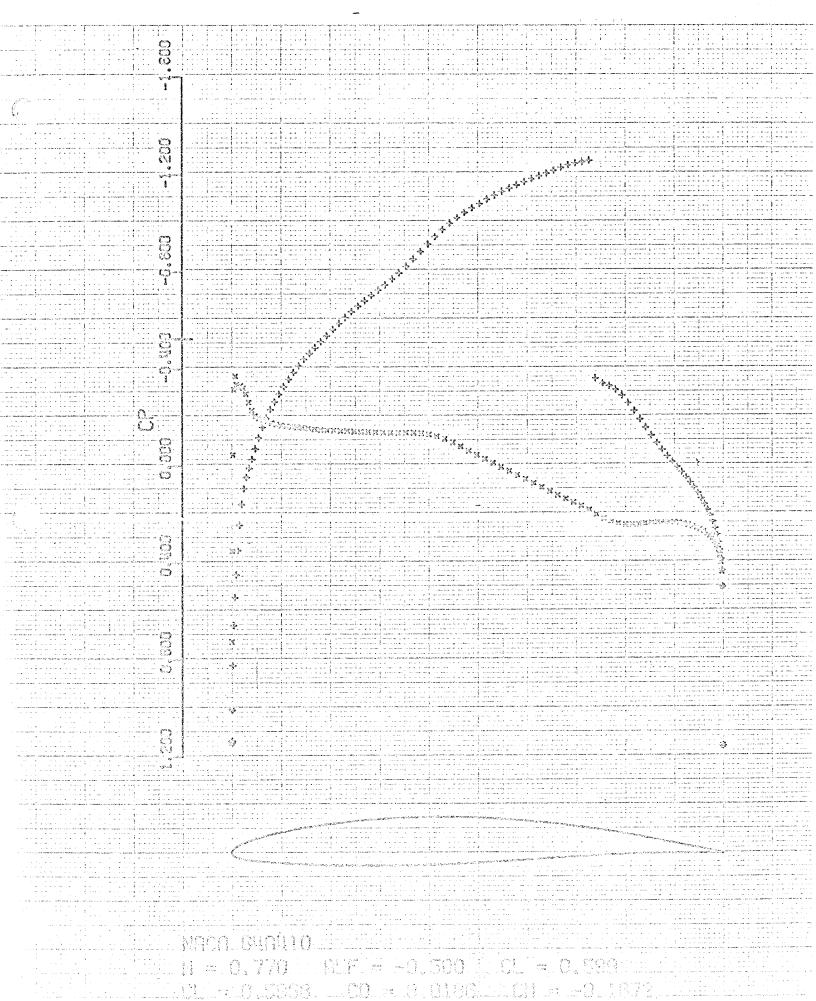


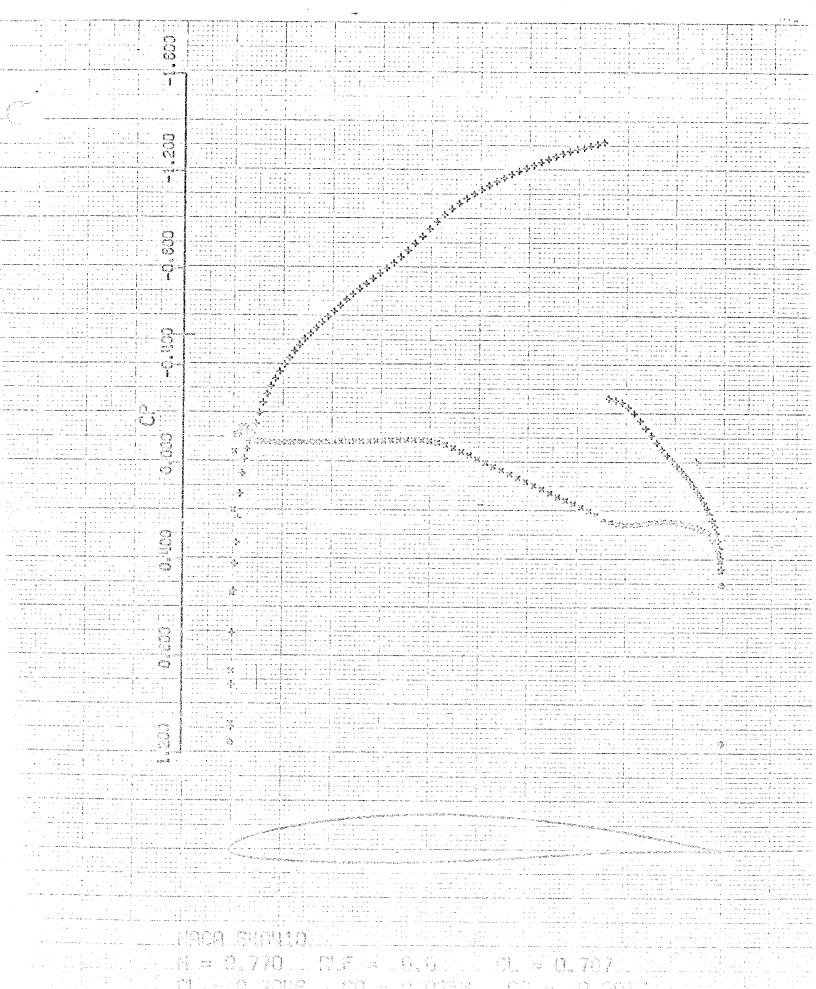


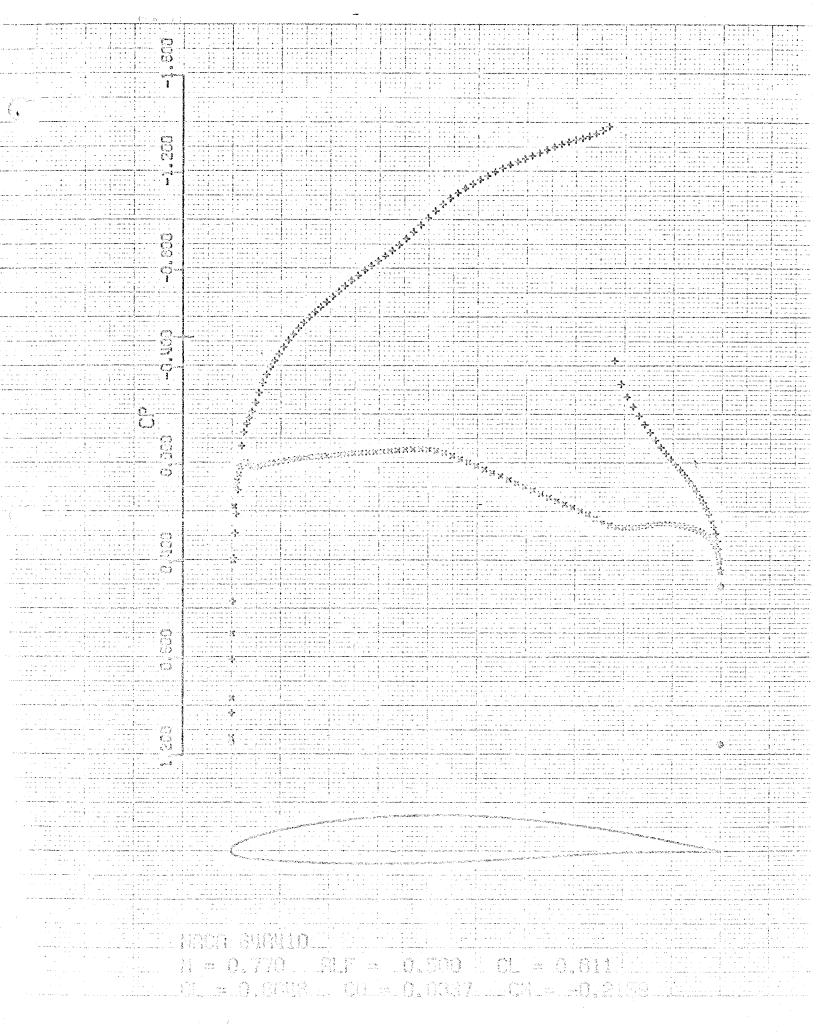
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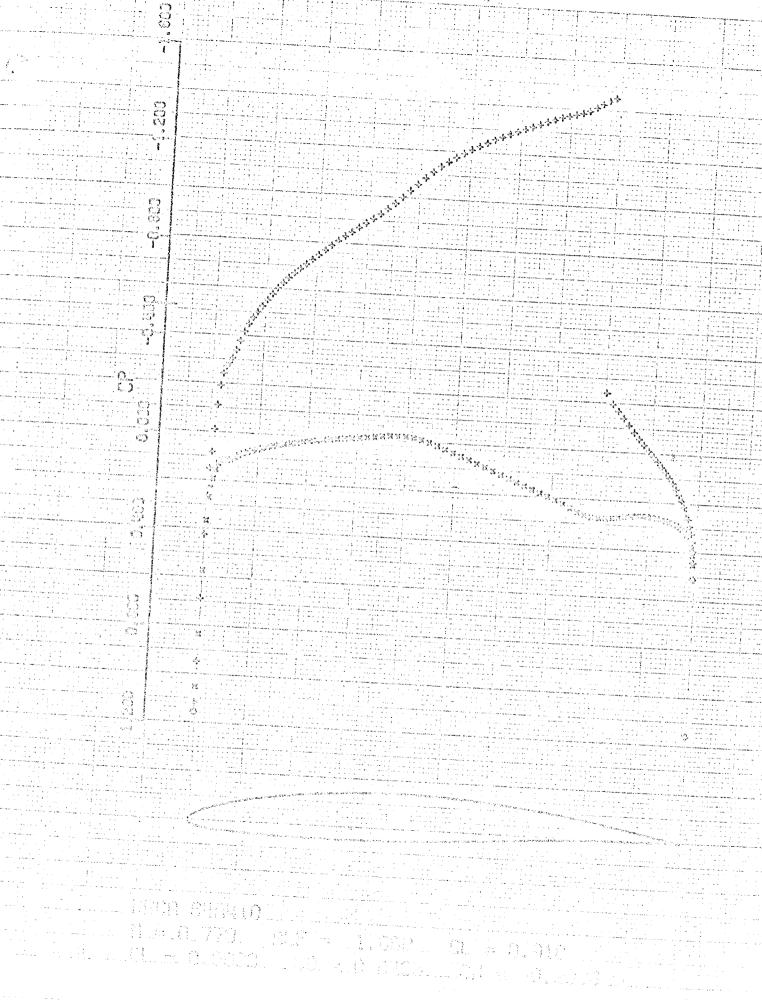










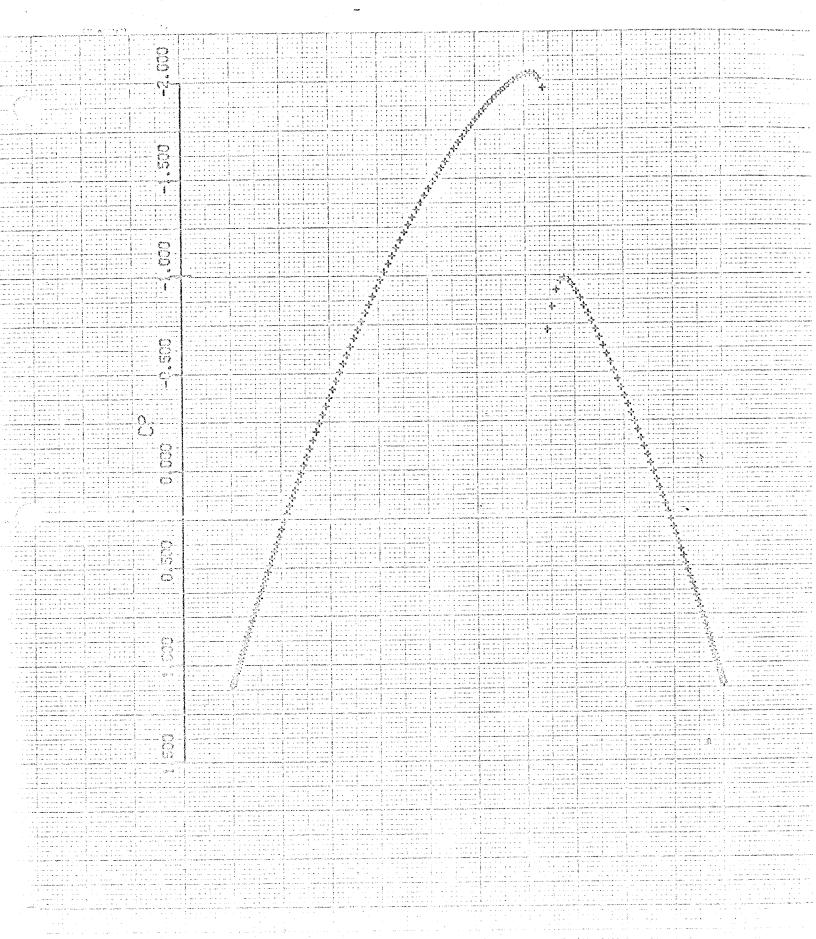


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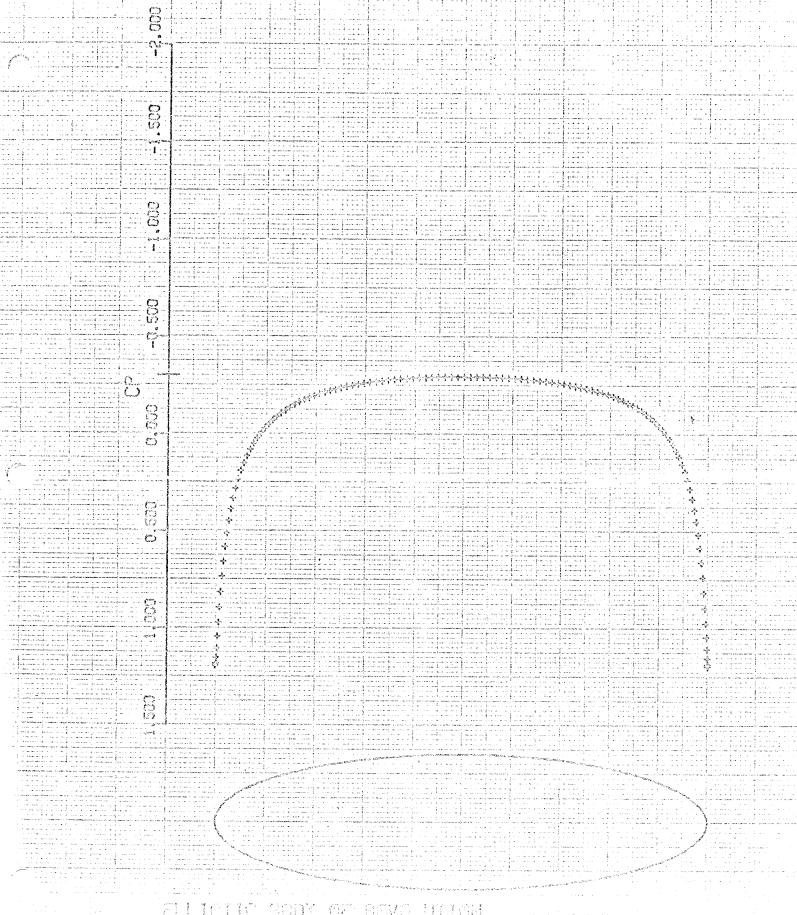
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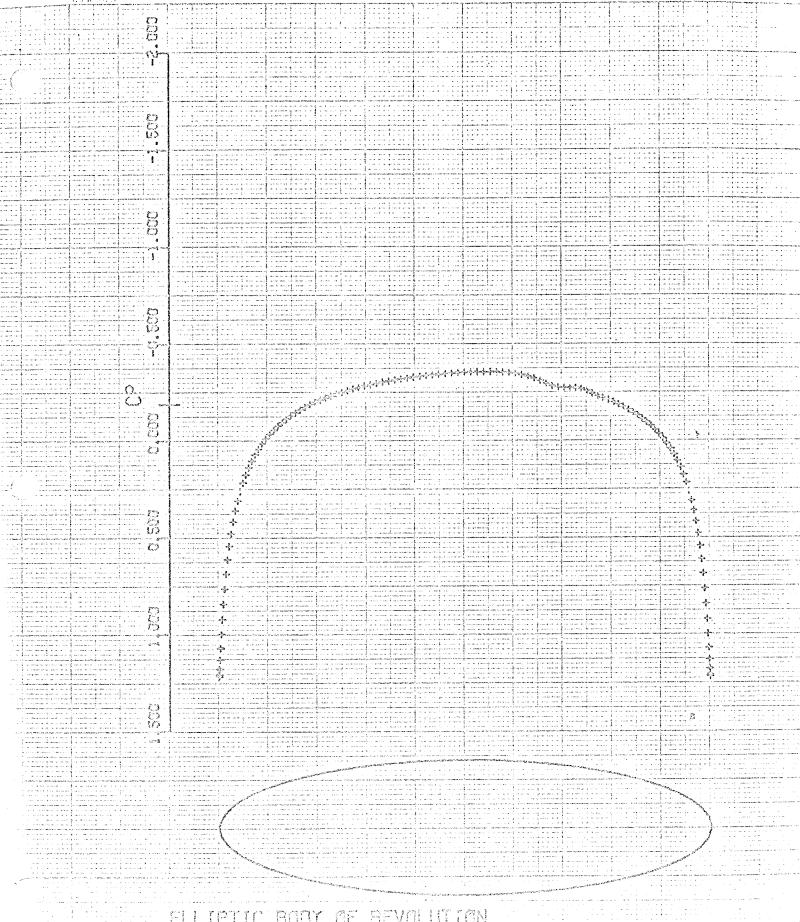


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## ELLIPTIC BODY OF REVOLUTION

Generated by Joukowsky mapping from unit circle with singular points at  $\pm\ .75$ 





ELLIPTIC BODY OF REVOLUTION

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